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PERSONAL INFO	Nationality: P.R.China	Gender: Male
PROFESSIONAL EXPERIENCE	2009 - 2013 (expected), <i>PhD candidate, Dynamics and Control, TU Eindhoven</i> <ul style="list-style-type: none"><li>• Research project: <b>Embedded Vision Architecture</b></li><li>• Supervisors: Prof. <b>Pieter Jonker</b>, Delft Biorobotics Lab, Faculty 3ME, TU Delft Prof. <b>Henk Corporaal</b>, Electronic Systems, Electrical Eng., TU Eindhoven Prof. <b>Henk Nijmeijer</b>, Dynamics &amp; Control, Mechanical Eng., TU Eindhoven</li><li>• My research in the project: Vision processing on field-programmable gate arrays (FPGAs) High-precision and high-speed visual servo control Modelling of cyber-physical systems</li></ul>	
RESEARCH INTERESTS	Computer Architecture, Computer Vision, Mechatronics	
EDUCATION	2009 - 2013 (expected), PhD candidate, TU Eindhoven, The Netherlands <ul style="list-style-type: none"><li>• Research Project: <b>Embedded Vision Architecture</b></li></ul> 2006 - 2009, MSc, TU Eindhoven, The Netherlands <ul style="list-style-type: none"><li>• Master Program: <b>Embedded Systems</b></li><li>• Master Thesis: <b>Architecture Exploration for Parallel Processing Systems</b>, supervised by Dr. <b>Bart Mesman</b> and Prof. <b>Henk Corporaal</b>.</li></ul> 2002 - 2006, B.S., Harbin Institute of Technology, P.R.China <ul style="list-style-type: none"><li>• Bachelor Program: <b>Electronics and Telecommunication</b></li></ul>	
SKILLS	Technical skills: <ul style="list-style-type: none"><li>• Electronic systems: processor architecture, application-specific circuit</li><li>• Parallel computing: algorithm and program optimization</li><li>• Computer vision: embedded vision processing, high-speed vision systems</li><li>• Mechatronics: precision motion control, visual servo control</li></ul> Language skills: Chinese (native), English (fluent)	